

IXSEA PHINS INERTIAL NAVIGATION SYSTEM



GENERAL DESCRIPTION

PHINS 6000 with DVL Ready Option, is a subsea inertial navigation system providing subsea vehicles with position, true heading, attitude, speed and heave. The high accuracy inertial measurement unit is based on FOG technology coupled with an embedded digital signal processor that runs an advanced Kalman filter.

FEATURES

- All-in-one 3D positioning with heading, roll and pitch
- unique strap-down technology
- Multiple interfaces (DVL, USBL, LBL, GPS and depth sensor
- DVL Ready option also available

BENEFITS

- Gain time and accuracy for all subsea projects
- Fibre Optic Gyroscope (FOG), No spinning element hence maintenance free
 - Smoothes and extends the capability of surface based USBL positioning systems (IXSEA's GAPS system) into even deeper water

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IXSEA PHINS INERTIAL NAVIGATION **SYSTEM**

TECHNICAL SPECIFICATIONS

PHINS 6000

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PERFORMANCE

Position accuracy (1)
With stand-alone GPS aiding
With differential GPS aiding
With RTK differential GPS aiding
With DVL aiding
No aiding for 2 minutes
No aiding for 5 minutes
Pure inertial mode

Heading accuracy (2) With GPS aiding With DVL aiding only

Roll and Pitch accuracy (2)

Heave accuracy

5 to 15 m

0.5 to 3 m 2 to 5 cm 0.1% of traveled distance (3 m/hr at 2 knots)

3 m 20 m 0.6 NM/hr

0.01 deg secant latitude ^[3] 0.02 deg secant latitude ^[3] 0.05 deg secant latitude ^[3]

5 cm or 5% (whichever is highest) Setup free: SAFE HEAVE™

OPERATING RANGE / ENVIRONMENT

Operating / Storage Temperature Calibration interval MTBF

Angular dynamic range Acceleration dynamic range Attitude range -10 to 50 °C / -40 to 80 °C

None required 30,000 hours < 500 deg/s ±5 g No limitation

PHYSICAL CHARACTERISTICS

Dimensions (Ø x H) Weight in air / water

DVL Ready option (WHN series compatible)
Dimensions (Ø x H) Weight in air / water Material

255 x 271 mm 20 kg / 14.5 kg Titanium

30 x 525 mm 45 kg / 30 kg Titanium

INTERFACES

RS 232/ RS 422 Data output rate **Output format** Power consumption Power supply 6 inputs, 6 outputs 0.1 Hz to 100 Hz

Based on industry standards (NMEA0183, ASCII, hexa or binary)

24 V nominal (from 20 to 30 V)

(1) CEP: Circular Error Probability 50 % - [2] Heading, Roll, Pitch figures are RMS values - (3) Secant latitude = 1 / cosine latitude

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